# Dataset IIIb: Non-stationary 2-class BCI data

### Short description:

cued motor imagery with online feedback (non-stationary classifier) with 2 classes, and 3 - 4 sessions from 3 subjects. (EEG, 2 bipolar channels)

#### Aim:

Non-stationary (i.e. time-varying) BCI data should be classified. It can be expected that time-varying classifier performs better than a stationary (static) classifier. Moreover, the response time of each method will be evaluated.

## EEG recording:

EEG-data from three different subjects during a BCI experiment. The experiment consists of 3 sessions for each subject. Each session consists of 4 to 9 runs. The data of all runs was concatenated and converted into the GDF format [1]. The recordings were made with a bipolar EEG amplifier from g.tec. The EEG was sampled with 125 Hz, it was filtered between 0.5 and 30Hz with Notchfilter on.

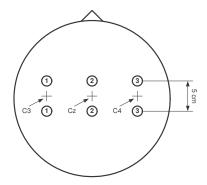
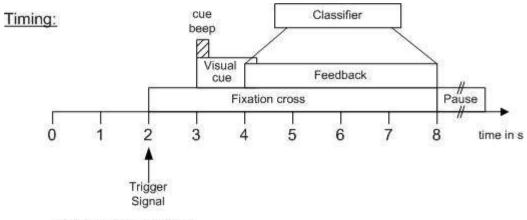


Figure 1: Electrode positions. Channel C3 and C4 are included in the EEG data.



Trial duration = 8000 ms
Trigger signal = 2000 ms
Ready Signal (Fixation cross) = [2000 - 8000] ms
Feedback = [4000 - 8000] ms
Cue Timing (visual) = [3000 - 4250] ms
Cue Beep (acoustic) = 3000 ms

Figure 2: Paradigm of the Virtual reality experiment used for O3. A comparible experiment is described in [2]

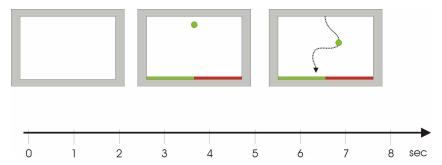


Figure 3: Basket paradigm used for S4 and X11 [3].

	Feedback	Feedback	Channels	# of	Classes
		presentation		Trials	
O3	Virtual reality [2]	4-8s	C3, C4	640	Left-Right
S4	Basket, adaptive	4-7s	C3, C4	1080	Left-Right
	classifier [3]				
X11	Basket, adaptive	4-7s	C3, C4	1080	Left-Right
	classifier [3]				

#### Format of the data

The data is stored in the GDF format [1] and can be loaded into Matlab or Octave with Biosig-toolbox [5] (version 0.81 or higher) using the command [s, HDR] = sload(filename). The data s can contain NaN's; these NaN's indicate the breaks in between the runs or saturation of the analog-to-digital converter.

All events are stored according to the Table of eventcodes [6]. The beginning of each trial (t = 0s according to Fig. 1) can be obtained from HDR.TRIG; the classlabels are stored in HDR.Classlabel. HDR.Classlabel can contain the values '1','2' or 'NaN'. Values '1' and '2' indicate the labels of the training set, NaN indicates the trials of the test set.

#### **Evaluation:**

Valid submissions must fulfill two requirements:

- (1) it must be demonstrated that the used algorithms are causal, at time t no sample from time k>t must be used (zero-phase filtering using forward-backward filters are not allowed). In order to demonstrate the causality, the source code of the algorithm must be submitted.
- (2) a continuous classification output (continuous in time as well as magnitude) must be submitted. The classifier output should provide a value<0 for class 1, a value > 0 for class 2, and value=0 is non-decisive.

The output will be validated using the time course of the mutual information [4]. The method with the maximum increase of the mutual information (maximum steepness calculated as MI(t)/(t-3s) for t>3.5s) will be used for validation. On order to avoid a stimulus-response-mechanism, time >3.5s will be evaluated. The "steepness" of the mutual information quantifies the response time. The evaluation algorithm is provided in BIOSIG (see /biosig/t490/criteria2005IIIb.m) [5].

#### Remark:

Optional, the algorithm can be submitted for inclusion into BIOSIG. Each algorithm which performs better than the standard classification algorithm [5] is eligible to be included in BIOSIG.

#### Contact:

Dipl.-Ing. Dr. Alois Schlögl e-mail: <a href="mailto:alois.schloegl@tugraz.at">alois.schloegl@tugraz.at</a>

#### References:

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- [6] available online:

http://cvs.sourceforge.net/viewcvs.py/biosig/biosig/t200/eventcodes.txt